Fig. 1

1   Initialization of the iteration counter
and the initial displacement field.

2   Numerical solution of the PDE for the
differential operator and the point evaluation
functionals located at the control points.

3   Combining the interpolation conditions.

4   Calculation of a specific, numerical solution
of the PDE for the differential operator
and the force based on the actual displacement.

5   Evaluation of the specific solution at the
control points.

6   Determination of the coefficients for
calculating an updated displacement.

7   Updating the displacement field and raising
the iteration counter.

8   Checking the displacement for convergence.

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